

IN THE SPECIFICATION:

Please add the following paragraph:

[0023.1] FIG. 5 shows another embodiment of a vehicle according to the present invention.

Please replace paragraph [0025] with the following amended paragraph:

[0025] On the frame 10 of the vehicle, wheel suspensions 6 and 7 for the rear wheels 2 and 3 are present, and for each of the rear wheels 2 and 3 its own steering drive 4 and 5. The steering drives 4 and 5 with this example are aligned transversely to the longitudinal axis of the vehicle and are designed as electrical linear drives which are activated by an electronic control which is not shown. The drives engage on shafts 2' and 3' behind the rear wheel suspensions 6 and 7, via which a pivoting may be effected on steering the rear wheels 2 and 3. Thereby, a gear transmission may be arranged therebetween, in order to be able to provide the required torques. At least one rotational angle sensor 20 may be present, which may be used for the control of the vehicle. Thus a rotational angle sensor provides a signal on the pivot angle of the front wheel. This signal may be used via an electronic control for the activation of the two steering drives and the drive of the rear wheels.

Please replace paragraph [0026] with the following amended paragraph:

[0026] The drives for the rear wheels 2 and 3 are electrical wheel hub motors which are likewise controlled. At least one further drive 15 may be situated on steering drive 4 and 5. The further drive may be one of a spindle drive and a rack drive.